PATENT

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Appl. No.

10/579,320

Applicant

Moustapha Hafez et al.

Filed

May 16, 2006

Title

"MULTI-STABLE ACTUATOR BASED ON SHAPE

MEMORY ALLOY AND TOUCH SENSITIVE

INTERFACE USING SAME"

Confirmation No.

TBD

TC/A.U.

TBD

Examiner

TBD

Customer No.

116

Docket No.

40426

INFORMATION DISCLOSURE STATEMENT

Mail Stop PCT Commissioner for Patents P.O. Box 1450 Alexandria, Va. 22313-1450

Sir/Madam:

In accordance with Rule 56, applicants are aware of the publications listed in the International Search Report (ISR, copy enclosed) and in the French Search Report (FSR, copy enclosed) of a corresponding French application, and in the enclosed copy of Patent Office Form 1449.

Since this Form 1449 is being filed as part of a U.S. Patent Application filed after June 30, 2003, a copy of each of the U.S. publications is not enclosed in accordance with the Patent Office waiver of 37 CFR 1.98(a)(2)(i), however, a copy of each other publication is enclosed.

I hereby certify that this correspondence is being deposited with the United States Postal Service as first class mail in an envelope addressed to: Mail Stop PCT, Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450 on the date indicated below.

Jeffrey J. Sopko

Name of Attorney for Applicant(s)

June.29, 2006

Date

Signature of Attorney

Application No.: 10/579,320

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If there are any fees required by this communication, please charge such fees to our Deposit Account No. 16-0820, Order No. 40426.

Respectfully submitted,

PEARNE & GORDON LLP

By:

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June 29, 2006

Form P10-1449	Form	PTO-1449
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ATTY. DOCKET NO. 40426

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INFORMATION DISCLOSURE CITATION

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(USE SEVERAL SHEETS IF NECESSARY)

APPLICANT: Moustapha Hafez et al.

FILING DATE:

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Examiner Initial		Document No.	Date	Name		Class	Sub	class	Filing Date If Appropriate	
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		OTHER REFER	ENCES (Inc	cluding Author, Title,	Date, Pertii	nent Pag	ges, Etc.,)		
	Q	-	sion Engineer	tion Principles for Fring, Vienna Univers			-			
	R	Hafez et al., "Optimized Binary Modular Reconfigurable Robotic Devices", Department of Mechanical Engineering, Massachusetts Institute of Technology, Cambridge, MA (English Text)								
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